# EE-100 Engineering Laboratory Module2: CAD

Dr. –Ing. Ahmad Kamal Nasir Office Hours: Room 9-245A Tuesday (1000-1100) Thursday (1000-1100)

### **CAD Module**

Learning Objective 1: Create and interpret mechanical drawings Learning Objective 2: Recall and demonstrate workshop/industrial safety practices.

- Week 1
  - Introduction to the course and its contents
  - Design methodology for scientists and engineers
  - Introduction to Engineering Drawing
  - Engineering Drawings
    - Standards, Types, Projections
  - Workshop / Industrial Safety Practices
  - Lab Tasks: Sketch orthographic projections of solid objects
  - Lab Visit: Overview of workshop facilities
- Week 2
  - Computer Aided Modeling
    - Intro to PTC Creo and its features
    - 2D sketching
    - Basics of 3D object modeling
  - Lab Tasks: 3D part modeling.

- Week 3
  - Advanced features of PTC Creo Parametric 2.0:
  - Lab Tasks: 3D part modeling
- Week 4
  - Assembly
  - Lab Task: Assembly task
- Week 5
  - Lab Task 9: Create parts and assembly drawings for a robotic hand (gripper)

### **Problem Statement**

In Engineering, a robotic arm gripper is required for effectively handling work in laboratory and home applications and industrial setups.

Usages:

- Pick and place
- Welding metals
- Grasping Objects
- Serving food in restaurants

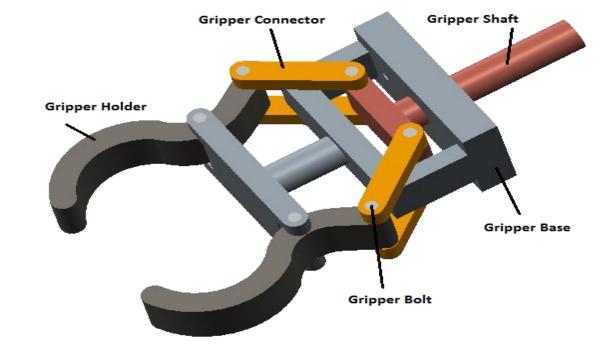


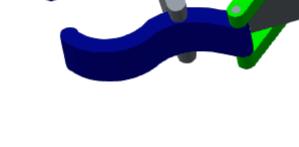




## **Simplest Solution**

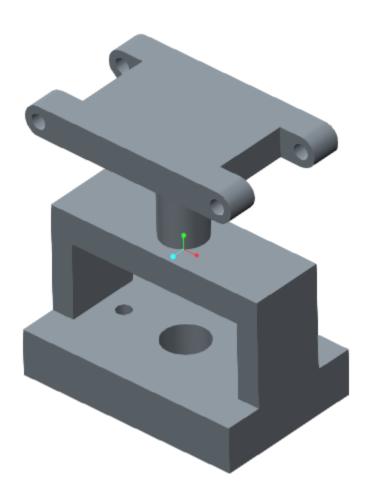
A 2-finger gripper is a perfect fit as it can easily hold the tools and work pieces. Following figure shows the 3D views of the proposed gripper design



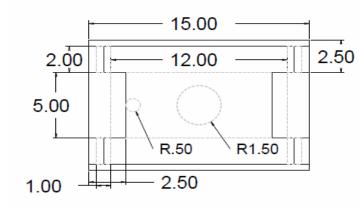


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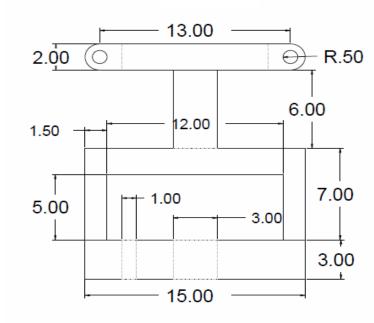
#### **Gripper Base**



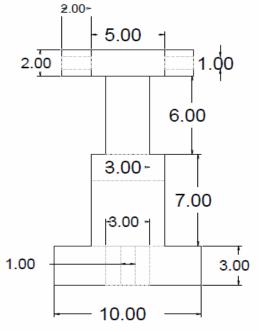


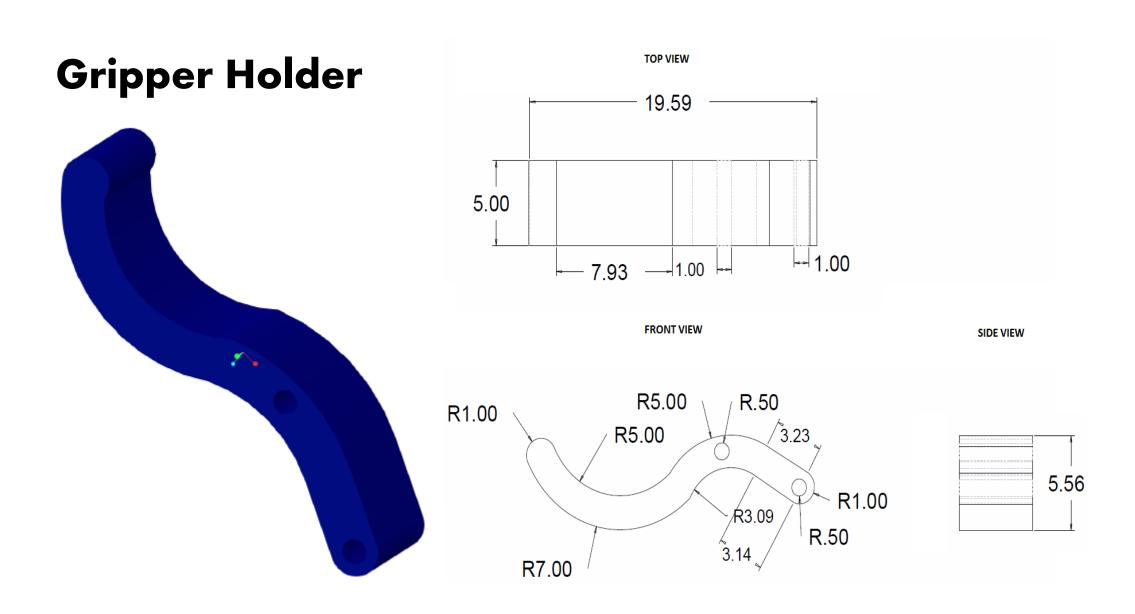


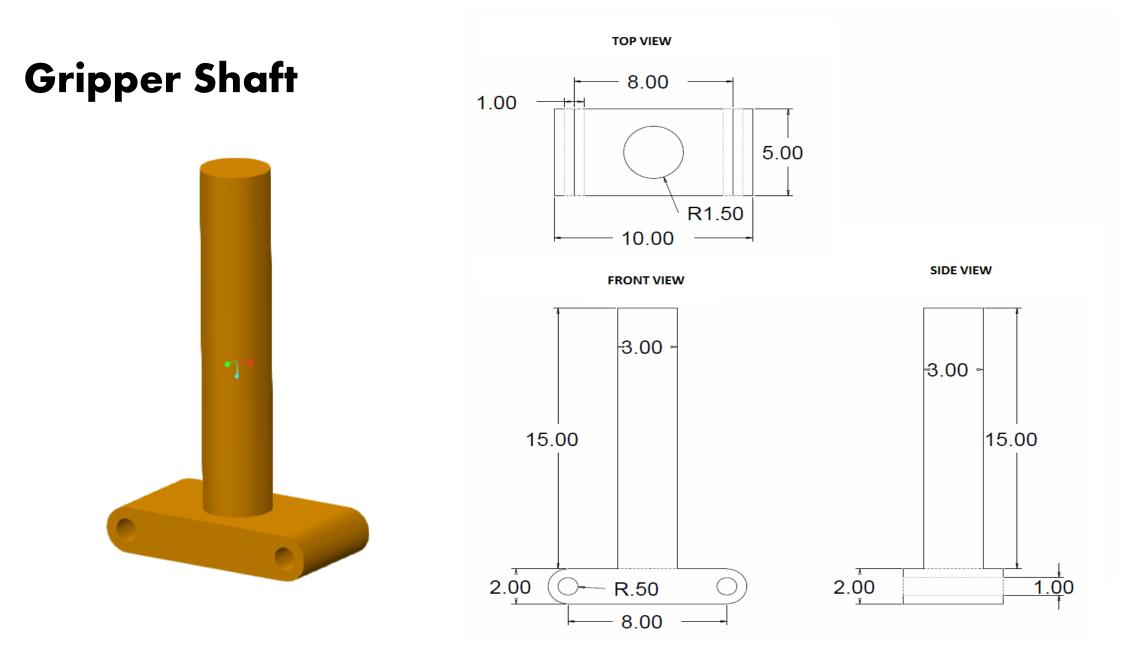
FRONT VIEW



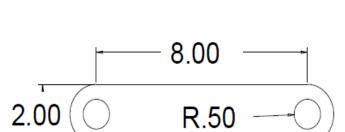








#### **Gripper Connector**



TOP VIEW

